
.....	1
.....	1
.....	1
(Matcher)	2
.....	2
.....	2
.....	2

points) (Minutiae) (Ending), (Bifurcation), (Singular
 (Matcher) (Feature extraction) 가



(Matcher)

가 가

CPU

, 가 ,
. PC

DSP

, TC FL



sensor A



sensor B

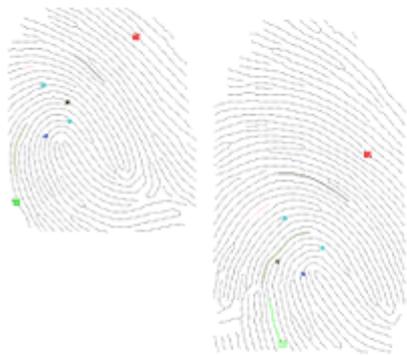


sensor C

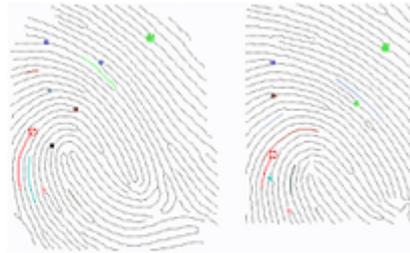


sensor D

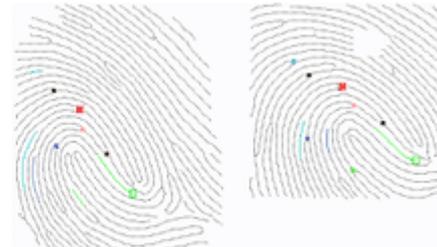
[]



Verification of A and B



Verification of A and C



Verification of A and D

[]

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